

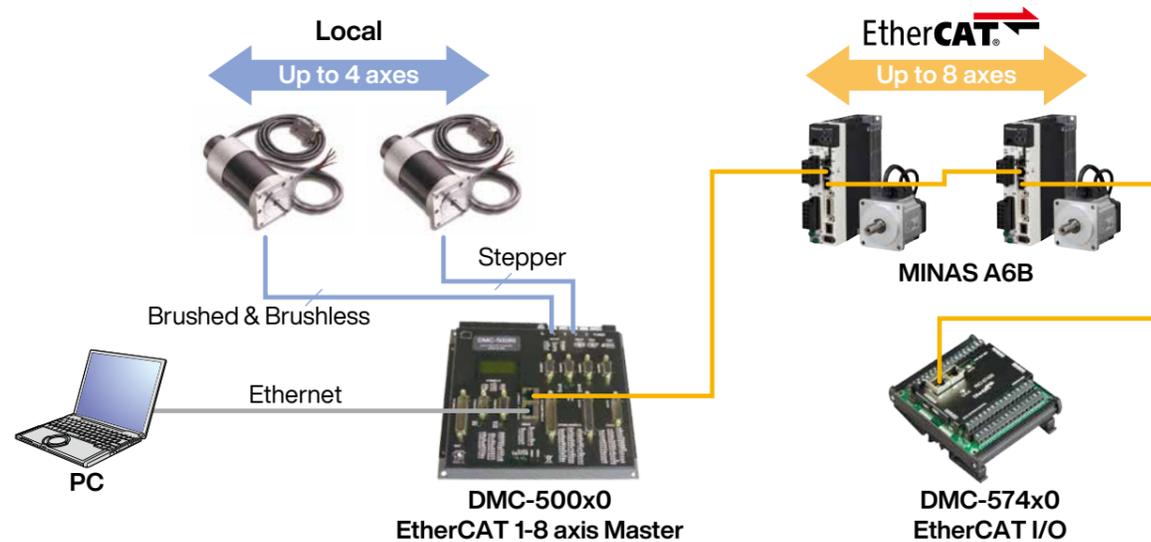
# EtherCAT Master Controller

Model DMC-50000

## Features

- Configurable controller for up to 8 axes of EtherCAT Master with any of the first 4 axes for local control or EtherCAT Master
- 10/100BASE-T Ethernet port; (1) EtherCAT Port; (2) RS232 ports up to 115 kbaud
- Available with internal, multi-axis servo or stepper drives. Or, connect to conventional external drives (only first four axes)
- For local axes, accepts up to 22 million counts per second of quadrature encoder for servos; Outputs up to 6 MHz for steppers; EtherCAT command speed up to 1 billion counts per second
- Sample times as low as 375 microseconds for 1-4 axes and 750 microseconds for 5-8 axes
- First four axes, advanced PID compensation with velocity and acceleration feedforward, integration limits, notch filter and low-pass filter
- Modes of motion include jogging, point-to-point positioning, position tracking, contouring, linear and circular interpolation, electronic gearing, ECAM and PVT
- Ellipse scaling, slow-down around corners, infinite segment feed and feed rate override
- Multitasking for concurrent execution of up to eight application programs
- Non-volatile memory for application programs (4000 Lines), variables and arrays (2400)
- Dual encoders for every local servo axis
- Optically isolated home input and forward and reverse limits for every local axis; Uses EtherCAT drive for home and limit switches
- Uncommitted, I/O:
  - 8 optically isolated inputs and 8 optically isolated outputs
  - Isolated, high-power outputs for driving brakes or relays (local axis only)
  - 8 uncommitted analog inputs
  - High speed position latch and output compare
  - 32 additional 3.3 V TTL I/O (5 V option)
  - More I/O available with RIO PLC
- 2 line x 8 character LCD
- Accepts single 20 - 80 VDC input
- Communication drivers for Windows and Linux
- Custom hardware and firmware options available

## System Configuration



# EtherCAT Master Controller

Model DMC-52000

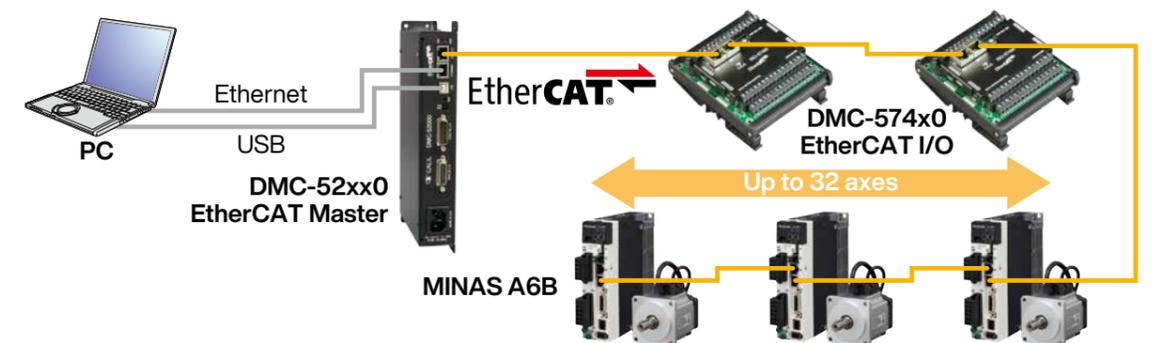
## Features

- Available in 2, 4, 8, 16, and 32 axis configurations
- 10/100BASE-T Ethernet port; (1) EtherCAT Port; (1) USB port
- EtherCAT cycle time 1000 microseconds
- Cyclic Synchronous Position mode (CSP)
- Modes of motion include jogging, point-to-point positioning, position tracking, contouring, linear and circular interpolation, electronic gearing, ECAM and PVT
- Ellipse scaling, slow-down around corners, infinite segment feed and feed rate override
- Multitasking for concurrent execution of up to eight application programs
- Non-volatile memory for application programs (4000 Lines), variables and arrays (2400)
- Inputs including forward limits, reverse limits, and homing inputs are located on drives that support these inputs
- Uncommitted, I/O:
  - 8 optically isolated inputs
  - 8 optically isolated high powered outputs
  - 8 uncommitted analog inputs
  - 8 uncommitted analog outputs
  - More I/O available with the RIO-47xxx or RIO-574x0
- Accepts single 120 - 240 VAC input
- Communication drivers for Windows and Linux

## Application Sample

Customer Stories URL: <http://www.galil.com/learn/customer-stories>  
Sample DMC Code URL: <http://www.galil.com/learn/sample-dmc-code>

## System Configuration



## Sales area

● United States of America  
Galil Headquarters in California  
World-wide sales network  
Please see our rep finder tool or contact us for more details.  
URL : <http://www.galil.com/order/find-reps-and-distributors>

## Language

● English

## For more information

URL : <http://www.galil.com/>



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